



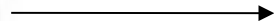
Acoustic Environment Recognition

Mentor: Hedieh Ekhlesi

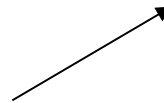
Roberto Soto, Axl Bryan Domingo,
Erika Perez



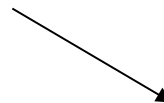
Recognizing the environment



www.downloadableyoutube.com



<http://upload.wikimedia.org/wikipedia/commons/f/f1/Oxford.street.london.arp.jpg>



<http://i2.cdn.turner.com/cnn/dam/assets>

Research Applications and Future Developments



www.hearing-aids-wizard.com

Data Samples

- 3 Environments: cafeteria, beach and street
- 30 samples of 20sec and 40sec lengths per environment
- Used 20 samples for training and 10 samples for testing purposes



UCSB entrance

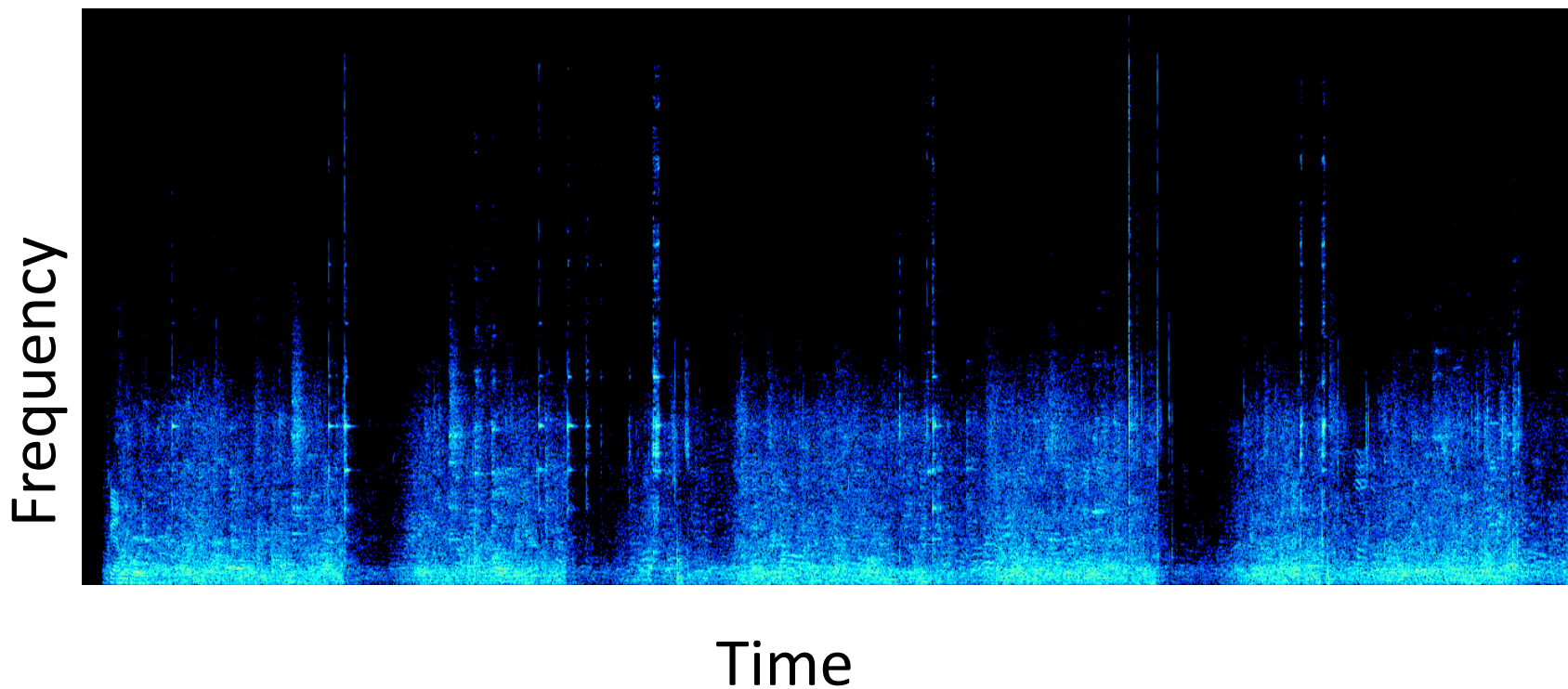


De La Guerra Cafeteria

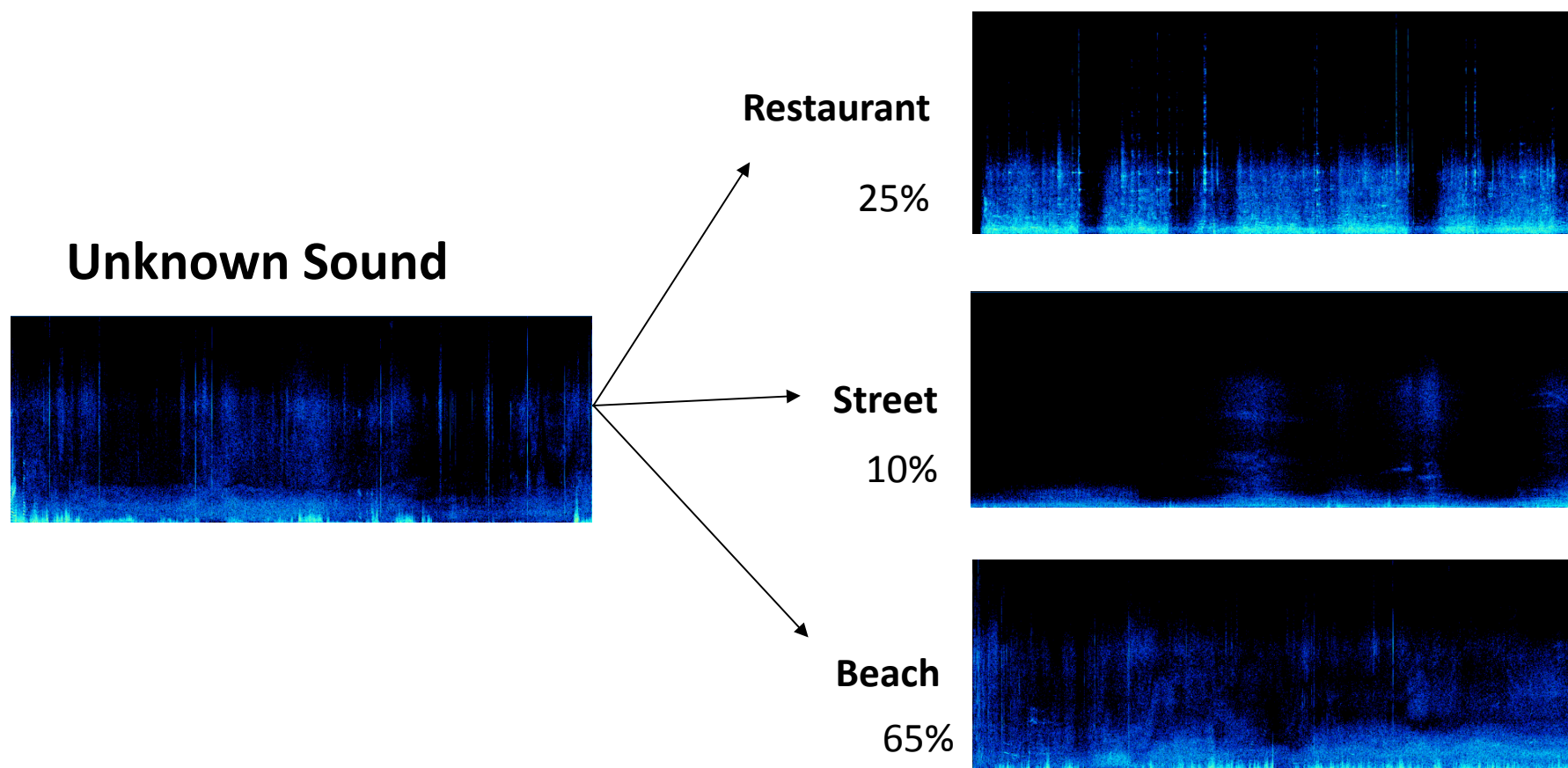


Goleta Beach

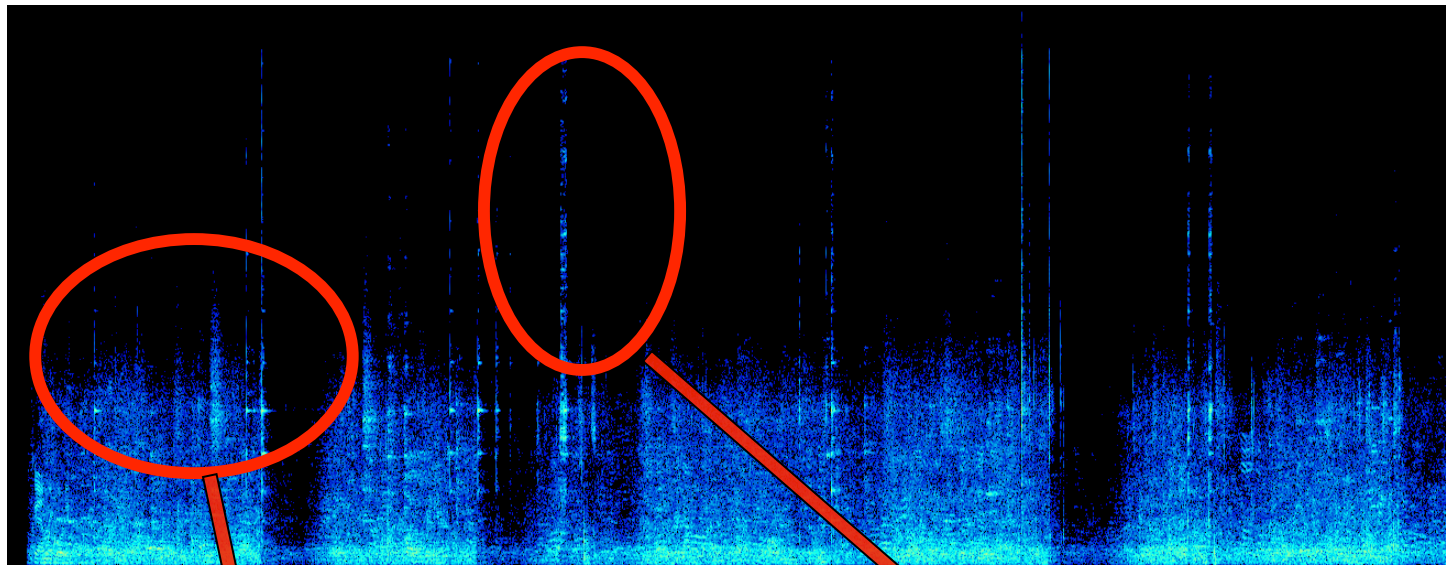
Spectrograms Represent Sounds



Recognizing Sounds

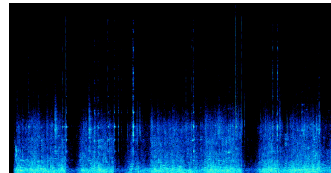


Hidden Markov Model

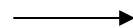


From sound to an environment

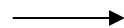
Testing Data:



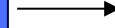
**Unknown
Sound**



**Feature
Extraction**



Decoder



**Recognized
Environment**



Model

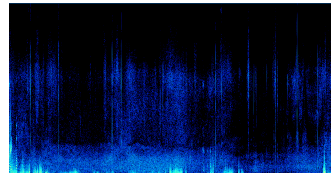


**Updating
Model**

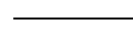


**Initializing
Model**

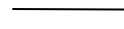
Training Data:



**Known
Sounds**



**Feature
Extraction**



Accuracy for 20 second samples

Accuracy %	Street	Beach	Restaurant
Street (10 samples)	4	3	3
Beach (10 samples)	2	4	4
Restaurant (10 samples)	0	0	10
Overall Accuracy: 61%			

Accuracy for 40 second samples

Accuracy %	Street	Beach	Restaurant
Street (10 samples)	10	0	0
Beach (11 samples)	6	1	4
Restaurant (10 samples)	0	0	10
Overall Accuracy: 67%			

Longer lengths = More accuracy

Future Improvements

- Better sound quality recording device
- Collecting more data samples
- Experiment with different data lengths
- Add more environments
- Finding the optimal number of states in Hidden Markov Model

Thank you!

Mentors:

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